Amendments to the Claims:

Claims 1 and 10 are amended as set forth hereinafter.

Listing of Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application.

1.   (Currently Amended)   A method for controlling a drive unit of a vehicle, the method comprising the steps of:

adjusting an output quantity of said drive unit in dependence upon desired value input quantities; ~~and,~~

5   assigning a priority to each of said desired value input quantities; and,

to make the adjustment of said output quantity, forming a desired value which considers said desired value input quantities in a sequence of their priorities.

2.   (Original)   The method of claim 1, wherein, when forming said desired value, the method comprises the further step of considering said desired value input quantities starting with the desired value input quantity having the lowest priority.

3.   (Previously Presented)   The method of claim 1, comprising the further step of coupling said desired value input quantities to different priorities, respectively.

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4. (Original) The method of claim 1, wherein said desired value input quantities limit said desired value or shift said desired value by an additive amount.

5. (Original) The method of claim 1, wherein a priority is permanently assigned to each one of said desired value input quantities.

6. (Original) The method of claim 1, wherein a priority is variably assigned to each one of said desired value input quantities.

7. (Original) The method of claim 6, wherein said priorities are assigned in dependence upon the operating state of said vehicle.

8. (Original) The method of claim 1, wherein different types of desired value input quantities are considered by different modules; and, the same types of desired value input quantities are each considered by a single module for forming said desired

5   value.

9. (Original) The method of claim 1, wherein a desired torque is selected as said desired value.

10. (Currently Amended) A method for controlling a drive unit of a vehicle, the method comprising the steps of:

    adjusting an output quantity of said drive unit in

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dependence upon desired quantity prescriptions; ~~and,~~

5   <u>assigning a priority to each of said desired quantity</u>

<u>prescriptions; and,</u>

to make the adjustment of said output quantity, forming a

desired quantity which considers said desired quantity

prescriptions in a sequence of their priorities.

11. (Previously Presented) The method of claim 10, wherein,

when forming said desired quantity, the method comprises the

further step of considering said desired quantity prescriptions

starting with the desired quantity prescription having the lowest

5   priority.

12. (Previously Presented) The method of claim 10, comprising

the further step of coupling said desired quantity prescriptions

to different priorities, respectively.

13. (Previously Presented) The method of claim 10, wherein said

desired quantity prescriptions limit said desired quantity or

shift said desired quantity by an additive amount.

14. (Previously Presented) The method of claim 10, wherein a

priority is permanently assigned to each one of said desired

quantity prescriptions.

15. (Previously Presented) The method of claim 10, wherein a

priority is variably assigned to each one of said desired

quantity prescriptions.

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16. (Previously Presented) The method of claim 15, wherein said priorities are assigned in dependence upon the operating state of said vehicle.

17. (Previously Presented) The method of claim 10, wherein different types of desired quantity prescriptions are considered by different modules; and, the same types of desired quantity prescriptions are each considered by a single module for forming

5   said desired quantity.

18. (Previously Presented) The method of claim 10, wherein a desired torque is selected as said desired quantity.

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